

Introduction to Circuit Quantum Electrodynamics

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INTERNATIONAL YEAR OF
Quantum Science
and Technology

1 The General Computational Process

- Classical bits
- Reversible operations on classical bits
- Quantum bits
- Reversible operations on quantum bits
- X-, Y-, Z-, and Hadamard gates

2 Control of the quantum bit

- Driven transmon Hamiltonian
- Two-level approximation
- Schrödinger equation of a drive qubit and its solution in the rotating frame
- Control signals
- Rotating Wave Approximation
- Z-control gate
- X-control gate
- Y-control gate

3 SWAP gate

- SWAP and iSWAP gates definition
- Two coupled transmons: Hamiltonian in the *weak-coupling* regime
- Two-level approximation
- Circuit Hamiltonian in a two-level approximation
- Schrödinger equation of a drive qubit and its solution in the rotating frame
- Coupled Qubits in the Rotating Wave Approximation
- Coordinates evolution and their matrix representation
- Bell state generation

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- Each position in such a string is called a bit, and it contains either a 0 or a 1.

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- Each position in such a string is called a bit, and it contains either a 0 or a 1.
- To represent such collections of bits the computer must contain a corresponding **collection of physical systems**, each of which can exist in two unambiguously distinguishable physical states, associated with the value (0 or 1) of the abstract bit that the physical system represents.
- Such a physical system could be, for example:
 - a **switch** that could be open (0) or shut (1)
 - a **magnet** whose magnetization could be oriented in two different directions, up (0) or down (1)

Classical bits

We represent the state of each classical bit with a box, depicted by the symbol $| \cdot \rangle$, and denoted as **ket**, into which we place the value 0 or 1

$$|0\rangle = \begin{matrix} 1 \\ 0 \end{matrix} ; \quad |1\rangle = \begin{matrix} 0 \\ 1 \end{matrix} ;$$

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several equivalent notations are currently in use

$$\begin{matrix} |0\rangle_2 & |1\rangle_2 & |2\rangle_2 & |3\rangle_2 \\ |0\rangle & |0\rangle & |1\rangle & |1\rangle \\ |0\rangle & |0\rangle & |1\rangle & |1\rangle \end{matrix}$$

Classical bits

The state of a pair of classical bits can be expressed as the tensor product of two classical bits

$$|x\rangle |y\rangle = \begin{pmatrix} x_0 \\ x_1 \end{pmatrix} \begin{pmatrix} y_0 \\ y_1 \end{pmatrix} = \begin{pmatrix} x_0 y_0 \\ x_0 y_1 \\ x_1 y_0 \\ x_1 y_1 \end{pmatrix}$$

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Reversible operations on one classical bit

reversible operations

An operation is **reversible** every final state arises from a unique initial state

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ERASE

$$\text{ERASE : } \begin{array}{l} |0\rangle \rightarrow |0\rangle \\ |1\rangle \rightarrow |0\rangle \end{array}$$

ERASE is **irreversible**: given only the final state, there is no way to recover the initial state.

Reversible operations on one classical bit

Identity

$$\mathbf{1} = \begin{array}{cc} /0 & - /0 \\ /1 & - /1 \end{array}$$

- we express the identity operation by a linear operator $\mathbf{1}$ acting on the two-dimensional vector space
- The action of $\mathbf{1}$ on the column vectors $/0$, $/1$ is given by a matrix

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NOT (bit flip)

$$\text{NOT} = \begin{array}{cc} /0 & - /1 \\ /1 & - /0 \end{array}$$

- The only non-trivial reversible operation we can apply to a single C-bit is the NOT
- NOT is reversible because it has an inverse: applying it a second time brings the state of the C-bit back to its original form.

$$\mathbf{X} = \begin{array}{cc} 0 & 1 \\ 1 & 0 \end{array}$$

Reversible operation on multiple classical bits

A very common 2-Cbit operator is the tensor product of two 1-Cbit operators

$$\mathbf{A} \otimes \mathbf{B} / xy = (\mathbf{A} \otimes \mathbf{B}) / x \otimes y = (\mathbf{A} / x) \otimes (\mathbf{B} / y)$$

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$$\mathbf{A} = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}; \quad \mathbf{B} = \begin{pmatrix} b_{11} & b_{12} \\ b_{21} & b_{22} \end{pmatrix}; \quad \mathbf{A} \otimes \mathbf{B} = \begin{pmatrix} a_{11}b_{11} & a_{11}b_{12} & a_{12}b_{11} & a_{12}b_{12} \\ a_{11}b_{21} & a_{11}b_{22} & a_{12}b_{21} & a_{12}b_{22} \\ a_{21}b_{11} & a_{21}b_{12} & a_{22}b_{11} & a_{22}b_{12} \\ a_{21}b_{21} & a_{21}b_{22} & a_{22}b_{21} & a_{22}b_{22} \end{pmatrix}$$

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The matrix representation of the 2-Cbit operator $\mathbf{X} \otimes \mathbf{X}$ in the basis $|0\rangle_2, |1\rangle_2, |2\rangle_2, |3\rangle_2$ is

$$\mathbf{X} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

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X X operation

$$\begin{array}{cccc}
 \mathbf{X} & \mathbf{X}/00 & = & \begin{array}{c} 0 \\ 0 \\ 0 \\ 1 \end{array} \\
 \begin{array}{cccc} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{array} & \begin{array}{c} 1 \\ 0 \\ 0 \\ 0 \end{array} & = & \begin{array}{c} 0 \\ 0 \\ 0 \\ 1 \end{array} \\
 & & & \text{---} \quad \text{---} \\
 & & & \quad /11
 \end{array}
 ; \quad
 \begin{array}{cccc}
 \mathbf{S}_{10}/01 & = & \begin{array}{c} 0 \\ 0 \\ 0 \\ 1 \end{array} \\
 \begin{array}{cccc} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{array} & \begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \end{array} & = & \begin{array}{c} 0 \\ 0 \\ 1 \\ 0 \end{array} \\
 & & & \text{---} \quad \text{---} \\
 & & & \quad /10
 \end{array}$$

$$\begin{array}{cccc}
 \mathbf{X} & \mathbf{X}/10 & = & \begin{array}{c} 0 \\ 0 \\ 0 \\ 1 \end{array} \\
 \begin{array}{cccc} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{array} & \begin{array}{c} 0 \\ 0 \\ 1 \\ 0 \end{array} & = & \begin{array}{c} 0 \\ 1 \\ 0 \\ 0 \end{array} \\
 & & & \text{---} \quad \text{---} \\
 & & & \quad /01
 \end{array}
 ; \quad
 \begin{array}{cccc}
 \mathbf{X} & \mathbf{X}/11 & = & \begin{array}{c} 0 \\ 0 \\ 0 \\ 1 \end{array} \\
 \begin{array}{cccc} 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 0 \end{array} & \begin{array}{c} 0 \\ 0 \\ 0 \\ 1 \end{array} & = & \begin{array}{c} 1 \\ 0 \\ 0 \\ 0 \end{array} \\
 & & & \text{---} \quad \text{---} \\
 & & & \quad /00
 \end{array}$$

Swap Operation

One reversible operation we can apply to 2 C-bits is the SWAP operation

$$S_{10} /xy - /yx$$

$$\left| \begin{array}{cc|c} /x & /y & S_{10} /xy \\ \hline 0 & 0 & 00 \\ 0 & 1 & 10 \\ 1 & 0 & 01 \\ 1 & 1 & 11 \end{array} \right|$$

The matrix representation of the 2-Cbit operator is

$$S_{10} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Swap Operation

$$\mathbf{S}_{10}/00 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{matrix} 1 \\ 0 \\ 0 \\ 0 \end{matrix} = \begin{matrix} 1 \\ 0 \\ 0 \\ 0 \end{matrix} \quad ; \quad \mathbf{S}_{10}/01 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{matrix} 0 \\ 1 \\ 0 \\ 0 \end{matrix} = \begin{matrix} 0 \\ 0 \\ 1 \\ 0 \end{matrix}$$

$\underline{\hspace{1cm}} \quad \underline{\hspace{1cm}}$
 $\underline{\hspace{1cm}} \quad \underline{\hspace{1cm}}$

$/00$
 $/10$

$$\mathbf{S}_{10}/10 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{matrix} 0 \\ 0 \\ 1 \\ 0 \end{matrix} = \begin{matrix} 0 \\ 1 \\ 0 \\ 0 \end{matrix} \quad ; \quad \mathbf{S}_{10}/11 = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{matrix} 0 \\ 0 \\ 0 \\ 1 \end{matrix} = \begin{matrix} 0 \\ 0 \\ 0 \\ 1 \end{matrix}$$

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Controlled C-not

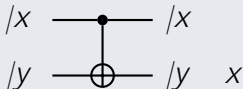
reversible operation we can apply to two Cbits is the controlled-not or cNOT C_{ij}

- State of the first C-bit (the control Cbit) is $/0$, then C_{10} leaves the state of the second Cbit (the target C-bit) unchanged
- if the state of the control C bit is $/1$, C_{10} applies the NOT operator to the state of the target C-bit.
- In either case the state of the control Cbit is left unchanged.

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- In either case the state of the control Cbit is left unchanged.

$$C_{10} |x\rangle |y\rangle = |x\rangle |y \oplus x\rangle$$

$$C_{10} = \begin{matrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \end{matrix}$$

The modulo-2 sum $x \oplus y$ is also called the “exclusive OR” (or XOR)

Permutations

The most general reversible operation on n C-bits in a classical computer is a permutation of the 2^n different basis states.

If $n = 2$, there are 4 basis states and $4!$ possible reversible operation

Qbits and their state

One Q-bit

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$$|\psi\rangle = c_0|0\rangle + c_1|1\rangle \quad \text{with } |c_0|^2 + |c_1|^2 = 1$$

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$$|\psi\rangle = \alpha|0\rangle + \beta|1\rangle \quad \text{with } |\alpha|^2 + |\beta|^2 = 1$$

$$|\psi\rangle = \alpha \begin{pmatrix} 1 \\ 0 \end{pmatrix} + \beta \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}$$

Qbits and their state

The state $|\psi\rangle$ is said to be a **superposition** of the states $|0\rangle$ and $|1\rangle$ with **amplitudes** α_0 and α_1 .

$$|\psi\rangle = \cos\frac{\theta}{2}|0\rangle + e^{i\phi}\sin\frac{\theta}{2}|1\rangle$$

$$0 < \theta < \pi; 0 < \phi < 2\pi$$

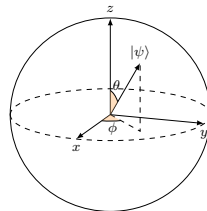


Figure: Bloch Sphere

Qbits and their state

Two Q-bits Quantum register

The state associated with a 2-qbits quantum register is a normalized **superposition** of the four classical basis states

$$= \frac{1}{2} |00\rangle + \frac{1}{2} |01\rangle + \frac{1}{2} |10\rangle + \frac{1}{2} |11\rangle$$

with the **normalization condition** $\frac{1}{2^2} + \frac{1}{2^2} + \frac{1}{2^2} + \frac{1}{2^2} = 1$

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$$= \begin{matrix} 1 \\ 0 \\ 0 \\ 0 \end{matrix} |00\rangle + \begin{matrix} 0 \\ 1 \\ 0 \\ 0 \end{matrix} |01\rangle + \begin{matrix} 0 \\ 0 \\ 1 \\ 0 \end{matrix} |10\rangle + \begin{matrix} 0 \\ 0 \\ 0 \\ 1 \end{matrix} |11\rangle$$

Product States vs Entangled States

A **particular** 2-Qbit state is generated by the tensor product of two 1-Qbit states and

$$= | \quad | = (a_0 |0\rangle + a_1 |1\rangle) (b_0 |0\rangle + b_1 |1\rangle) = \begin{matrix} a_0 & b_0 \\ a_1 & b_1 \end{matrix} = \begin{matrix} a_0 b_0 \\ a_0 b_1 \\ a_1 b_0 \\ a_1 b_1 \end{matrix}$$

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Bell States

$$^{\pm} = \frac{|00\rangle \pm |11\rangle}{\sqrt{2}} \quad ^{\pm} = \frac{|01\rangle \pm |10\rangle}{\sqrt{2}}$$

This generalizes to n Qbits, whose state is a superposition of the 2^n different classical states,

$$| \psi \rangle = \sum_{x=0}^{2^n-1} \alpha_x |x\rangle$$

with amplitudes whose squared magnitudes sum to unity $\sum_{x=0}^{2^n-1} |\alpha_x|^2 = 1$

Unitary transformation

- The only nontrivial reversible operation a classical computer can perform on a single C-bit is the NOT operation \times

Unitary operators

$$UU^\dagger = U^\dagger U = 1$$

Unitary transformation

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- The most general reversible operations that a quantum computer can perform upon a single Q-bit are represented by the action on the state of the Qbit of any **linear transformation** that takes **unit vectors into unit vectors**

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Unitary operators

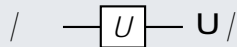
$$UU^\dagger = U^\dagger U = 1$$

- U is a **unitary** transformation, represented by a unitary matrix
- Since any unitary transformation has a unitary inverse, such actions of a quantum computer on a Qbit are **reversible**

Block diagrams

The action of a sequence of gates acting on n Qbits may be represented by block diagrams:

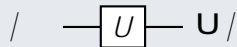
- Initially, the Qbit is described by the input state $| \psi \rangle$.
- The thin line (wire) guides us through the subsequent history of the Qbit.



Block diagrams

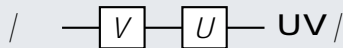
The action of a sequence of gates acting on n Qbits may be represented by block diagrams:

- Initially, the Qbit is described by the input state $| \psi \rangle$.
- The thin line (wire) guides us through the subsequent history of the Qbit.
- After emerging from the box representing U , the Qbit is described by the final state $U | \psi \rangle$.



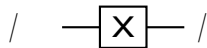
Block diagrams

- Initially, the Qbits are described by the input state on the left.
- They are acted upon first by the gate V and then by the gate U
- they emerging on the right in the final state UV / .



The order in which the Qbits encounter unitary gates in the figure is opposite to the order in which the corresponding symbols are written in the symbol for the final state on the right.

X-gate (qubit flip)

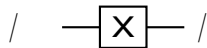


$$\mathbf{X} = \begin{matrix} |0\rangle & - & |1\rangle \\ |1\rangle & - & |0\rangle \end{matrix}$$

Representation of the X-gate in the basis $\{|0\rangle$

$$\mathbf{X} = \begin{matrix} 0 & 1 \\ 1 & 0 \end{matrix}$$

X-gate (qubit flip)

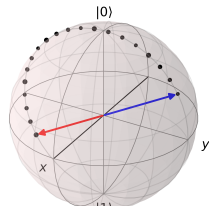


$$\mathbf{X} = \begin{matrix} x: & |0\rangle & - & |1\rangle \\ & |1\rangle & - & |0\rangle \end{matrix}$$

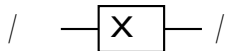
Representation of the X-gate in the basis $\{|0\rangle, |1\rangle\}$

$$\mathbf{X} = \begin{matrix} x = & 0 & 1 \\ & 1 & 0 \end{matrix}$$

In a Bloch sphere representation, the X-gate performs a rotation of π around the x -axis



X -gate (arbitrary rotation around the x-axis)

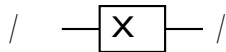


Representation of the X in the basis $\{|0\rangle, |1\rangle\}$

$$X = \begin{pmatrix} -i \cos \frac{\alpha}{2} & \sin \frac{\alpha}{2} \\ \sin \frac{\alpha}{2} & -i \cos \frac{\alpha}{2} \end{pmatrix}$$

- In the Bloch sphere representation, the X -gate performs a rotation of α around the X-axis

X -gate (arbitrary rotation around the x-axis)



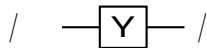
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- In the Bloch sphere representation, the X -gate performs a rotation of α around the X-axis
- For example, if $\alpha = \pi/2$ we have:

$$X_{\pi/2} = \frac{1}{\sqrt{2}} \begin{pmatrix} -i & 1 \\ 1 & -i \end{pmatrix}$$

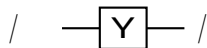
Y-gate



Matrix representation of the \mathbf{Y} -gate in the basis $\{|0\rangle, |1\rangle\}$

$$\mathbf{Y} = y: \begin{array}{cc} |0\rangle & -i|1\rangle \\ |1\rangle & -i|0\rangle \end{array}$$

$$\mathbf{Y} = y = \begin{array}{cc} 0 & -i \\ i & 0 \end{array}$$



Matrix representation of the \mathbf{Y} -gate in the basis $\{|0\rangle, |1\rangle\}$

$$\mathbf{Y} = \begin{matrix} y: & \begin{matrix} |0\rangle & -i|1\rangle \\ |1\rangle & -i|0\rangle \end{matrix} \end{matrix}$$

$$\mathbf{Y} = \begin{matrix} y = & \begin{matrix} 0 & -i \\ i & 0 \end{matrix} \end{matrix}$$

In a Bloch sphere representation, the \mathbf{Y} -gate performs a rotation of π around the y -axis

Y -gate (arbitrary rotation around the x-axis)

Representation of the Y -gate in the basis $\{|0\rangle, |1\rangle\}$



$$Y = \begin{pmatrix} -i \cos \frac{\gamma}{2} & \sin \frac{\gamma}{2} \\ \sin \frac{\gamma}{2} & -i \cos \frac{\gamma}{2} \end{pmatrix}$$

- In the Bloch sphere representation, the Y -gate performs a rotation of γ around the y -axis

Y -gate (arbitrary rotation around the x-axis)

Representation of the Y -gate in the basis $\{|0\rangle, |1\rangle\}$

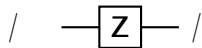


$$Y = \begin{pmatrix} -i \cos \frac{\gamma}{2} & \sin \frac{\gamma}{2} \\ \sin \frac{\gamma}{2} & -i \cos \frac{\gamma}{2} \end{pmatrix}$$

- In the Bloch sphere representation, the Y -gate performs a rotation of γ around the y -axis
- For example, if $\gamma = \pi/2$ we have:

$$Y_{\pi/2} = \frac{1}{2} \begin{pmatrix} -i & 1 \\ 1 & -i \end{pmatrix}$$

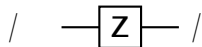
Z-gate



$$\mathbf{Z} : \begin{array}{l} |0\rangle \rightarrow -|0\rangle \\ |1\rangle \rightarrow +|1\rangle \end{array}$$

Matrix representation of the **Z**-gate in the basis $\{|0\rangle, |1\rangle\}$

$$\mathbf{Z} = \begin{array}{cc} -1 & 0 \\ 0 & +1 \end{array}$$



$$\mathbf{Z} : \begin{array}{l} |0\rangle \rightarrow -|0\rangle \\ |1\rangle \rightarrow +|1\rangle \end{array}$$

Matrix representation of the **Z**-gate in the basis $\{|0\rangle, |1\rangle\}$

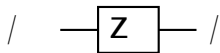
$$\mathbf{Z} = \begin{array}{cc} -1 & 0 \\ 0 & +1 \end{array}$$

In a Bloch sphere representation, the **Z**-gate performs a rotation of π around the Z-axis

Z -gate

arbitrary rotation around the Z-axis

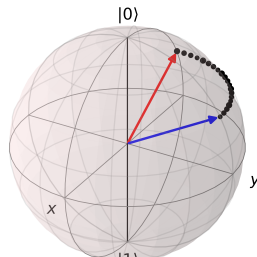
Representation of the Z -gate in the basis $\{|0\rangle, |1\rangle\}$



$$Z = \begin{pmatrix} -1 & 0 \\ 0 & -e^{-i} \end{pmatrix}$$

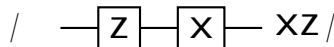
- In a Bloch sphere representation, the Z-gate performs a rotation of π around the Z-axis

$$Z_{\frac{\pi}{2}} = \begin{pmatrix} -1 & 0 \\ 0 & i \end{pmatrix}$$



The order in which we apply the gates is very important (non-commutative)

$$[\mathbf{X}, \mathbf{Z}] = 0$$

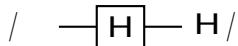


\mathbf{X} anticommutes with \mathbf{Z}

$$\mathbf{ZX} = -\mathbf{XZ}$$

Hadamard Gate

Definition



$$H = \frac{X - Z}{2} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$$H|0\rangle = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{2} (|0\rangle + |1\rangle)$$

$$H|1\rangle = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \frac{1}{2} (|0\rangle - |1\rangle)$$

One **degree of freedom**: flux $\hat{\phi}$;

\hat{q} is the **conjugate variable** to

$\phi_0 = 2\pi \frac{\hbar}{2e} \Phi_0$ is the flux quantum

$$E_C = \frac{(2e)^2}{2C}$$

E_J is the Josephson Energy

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$$E_C = \frac{(2e)^2}{2C}$$

E_J is the Josephson Energy

$$\hat{H}(\hat{q}, \hat{\varphi}; t) = \hat{H}_a + \hat{H}_{drive} = \frac{\hat{q}^2}{2C} + E_J \left[1 - \cos \left(2\pi \frac{\hat{\varphi}}{\varphi_0} - j(t) \right) \right]$$

$$j(t) = J_m f(t) \quad J_m = \max_t |j(t)|$$

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$$f(t) = s(t) \sin(\omega_d t + \phi)$$

$s(t)$ is the envelope function

$\sin(\omega_d t + \phi)$ is the high frequency carrier

$$j(t) = J_m f(t) \quad J_m = \max_t |j(t)|$$

$$f(t) = s(t) \sin(\omega_d t + \phi)$$

$$f(t) = s(t) \left[\underbrace{\cos(\phi)}_I \sin(\omega_d t) + \underbrace{\sin(\phi)}_Q \cos(\omega_d t) \right] = s(t) [I \sin(\omega_d t) + Q \cos(\omega_d t)]$$

$s(t)$ is the envelope function

$\sin(\omega_d t + \phi)$ is the high frequency carrier

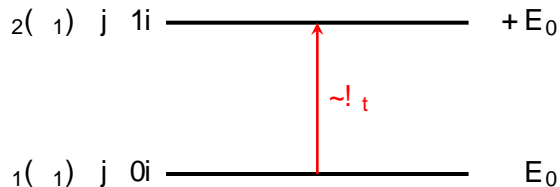
$I = \cos \phi$ is the in-phase component

$Q = \sin \phi$ is the out-of-phase component

Two-level approximated model: Transmon

The transmon has **is nitely many** non-degenerate energy eigenstates

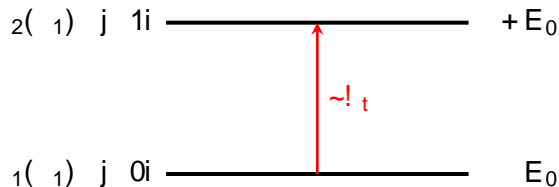
its spectral lines are associated with transitions between any pair of energy eigenstates.



Two-level approximated model: Transmon

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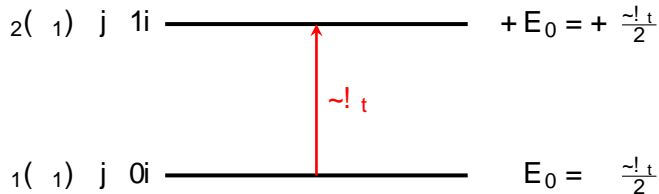
If the following hypotheses hold:

large anharmonicity

the frequency involved is such that only transitions between the two lowest levels are allowed

The dynamics of the transmon qubit is obtained by **the lowest energy levels**

Two-level approximated model: Transmon



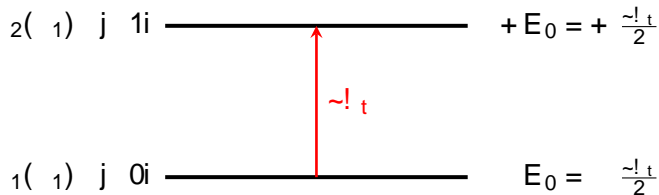
$$\hbar t = \frac{q}{8E_C j E_J} \frac{E_C}{\sim}$$

$$\mathcal{H}_a = \frac{\hbar t}{2} \hat{\Lambda}_z$$

$\hat{\Lambda}_z$ definition

$$\begin{cases} \hat{\Lambda}_z |0\rangle = - |0\rangle \\ \hat{\Lambda}_z |1\rangle = + |1\rangle \end{cases}$$

Two-level approximated model: Transmon



$$\hat{H}_{\text{drive}} = \hbar\omega_C \hat{n}$$

$$\hat{H}_{\text{drive}} = \hbar\omega_C \hat{n} + \hbar\omega_C \hat{n}^2$$

$$\hat{H} = \sum_{n=0}^{\infty} \left(\frac{\hbar\omega_C}{2} + \hbar\omega_C n \right) |n\rangle\langle n|$$

\hat{X} definition

$$\begin{aligned} \hat{X} |0\rangle &= |1\rangle \\ \hat{X} |1\rangle &= |0\rangle \end{aligned}$$

$$\omega_t = \frac{q}{8E_C J E_J} \frac{E_C}{\hbar}$$

$$T = \frac{2\pi}{\omega_t} \sum_{n=0}^{\infty} \left(\frac{1}{2} \right)^n \left(\frac{1}{2} \right)^n$$

$$j(t) = J_m f(t);$$

$$f(t) = s(t) \sin(\omega_d t + \phi); \quad J_m = \max_t |s(t)| g$$

$$= J_m T \approx \dots$$

two-level Hamiltonian

$$\hat{H} = \frac{\hbar \omega_t}{2} \hat{\Lambda}_z + \hbar f(t) \hat{\Lambda}_x$$

$\hat{\Lambda}_z$ definition

$$\begin{aligned} \hat{\Lambda}_z |j0\rangle &= |j0\rangle \\ \hat{\Lambda}_z |j1\rangle &= -|j1\rangle \end{aligned}$$

$\hat{\Lambda}_x$ definition

$$\begin{aligned} \hat{\Lambda}_x |j0\rangle &= |j1\rangle \\ \hat{\Lambda}_x |j1\rangle &= |j0\rangle \end{aligned}$$

Qubit control & Logic Gates

The **state** of the circuit at time t is approx. described by the ket $|j(t)\rangle$ in a 2D Hilbert space

$$|j(t)\rangle = c_0(t) |j0\rangle + c_1(t) |j1\rangle$$

$|c_0(t)|^2$ yields the probability that the outcome of the measurement of energy of the qubit at time t is E_0

$|c_1(t)|^2$ yields the probability that at time t the outcome of the measurement of energy of the qubit is E_1

$$|j(0)\rangle = c_0(0) |j0\rangle + c_1(0) |j1\rangle$$

Qubit control & Logic Gates

The **state** of the circuit at time t is approx. described by the ket $|j(t)\rangle$ in a 2D Hilbert space

$$|j(t)\rangle = c_0(t)|j0\rangle + c_1(t)|j1\rangle$$

$|c_0(t)|^2$ yields the probability that the outcome of the measurement of energy of the qubit at time t is E_0

$|c_1(t)|^2$ yields the probability that at time t the outcome of the measurement of energy of the qubit at time t is $E_1 + E_0$

At $t = 0$ the state of the quantum circuit is $|j(0)\rangle = |j_0\rangle$

$$|j(0)\rangle = c_0(0)|j0\rangle + c_1(0)|j1\rangle$$

Qubit control & Logic Gates

The **state** of the circuit at time t is approx. described by the $|j(t)\rangle$ in a 2D Hilbert space

$$|j(t)\rangle = c_0(t)|j0\rangle + c_1(t)|j1\rangle$$

To find the state of the quantum circuit $|j(t)\rangle$ at time t , we have to solve the Schrödinger equation

$$i\hbar \frac{d|j(t)\rangle}{dt} = \left[\frac{\hbar \omega}{2} \hat{\sigma}_z + f(t) \hat{\sigma}_x \right] |j(t)\rangle$$

$$|j(t_0)\rangle = |j0\rangle$$

Variable transformation: rotating frame

$$i \frac{d\mathbf{j}(t)}{dt} = \frac{\omega}{2} \hat{z} \cdot \mathbf{j}(t)$$

We solve the problem in a new variable \mathbf{j}^0 .

Variable transformation: rotating frame

$$i \frac{d\mathbf{j}^Q(t)}{dt} = \frac{\omega}{2} \hat{z} + f(t) \hat{x} \mathbf{j}^Q(t)$$

We solve the problem in a new variable \mathbf{j}^Q .

At time t , the Bloch sphere representation of \mathbf{j}^Q is rotated clockwise about the z -axis by an angle $\theta(t) = + \omega t$ with respect to the Bloch sphere representation \mathbf{j} .

Variable transformation: rotating frame

$$i \frac{d|j(t)\rangle}{dt} = \frac{\omega}{2} \hat{z} |j(t)\rangle - f(t) \hat{x} |j(t)\rangle$$

We solve the problem in a new variable $|j^0\rangle$.

At time t , the Bloch sphere representation of $|j^0\rangle$ is rotated clockwise about the z -axis by an angle $\theta(t) = + \omega t$ with respect to the Bloch sphere representation of $|j^0\rangle$.

$$\mathcal{R}_z(\theta(t)) = e^{i\theta(t)\hat{z}}$$

$$|j(t)\rangle = \mathcal{R}_z(\theta(t)) |j^0\rangle \quad \text{where} \quad \mathcal{R}_z(\theta(t)) = \exp\left(-i\theta(t)\frac{\hat{z}}{2}\right) \quad \theta(t) = \omega t$$

Variable transformation: rotating frame

$$i \frac{d\mathbf{j}(t)}{dt} = \frac{\omega}{2} \hat{z} + f(t) \hat{x} \mathbf{j}(t)$$

We solve the problem in a new variable $\tilde{\mathbf{j}}$.

At time t , the Bloch sphere representation of $\tilde{\mathbf{j}}$ is rotated clockwise about the z -axis by an angle $\theta(t) = + \int_0^t \omega dt$ with respect to the Bloch sphere representation of \mathbf{j} .

Variable transformation: rotating frame

$$i \frac{d\mathbf{j}(t)}{dt} = \frac{\omega}{2} \hat{z} + f(t) \hat{x} \mathbf{j}(t)$$

We solve the problem in a new variable \mathbf{j}^0 .

At time t , the Bloch sphere representation of \mathbf{j}^0 is rotated clockwise about the z -axis by an angle $\theta(t) = + \int_0^t \omega dt$ with respect to the Bloch sphere representation of \mathbf{j} .

$$i \frac{d\mathbf{j}^0}{dt} = \frac{\omega}{2} \hat{z}^0 + f(t) \hat{x}^0 \mathbf{j}^0$$

We have to find the expression of the operators \hat{z}^0, \hat{x}^0 in the rotating frame.

Variable transformation: rotating frame

$$i \frac{d}{dt} \psi = \frac{\hbar \omega}{2} \hat{z}^0 \psi + f(t) \hat{x}^0 \psi$$

$$\begin{cases} \hat{z}^0 = \hat{R}_z^y \hat{z} \hat{R}_z \\ \hat{x}^0 = \hat{R}_z^y \hat{x} \hat{R}_z \end{cases}$$

$$\begin{cases} \hat{z}^0 = \hat{R}_z^y \hat{z} \hat{R}_z = \hat{z} \\ \hat{x}^0(t) = \hat{R}_z^y \hat{x} \hat{R}_z = \hat{x} \cos(\omega t) + \hat{y} \sin(\omega t) \end{cases}$$

Variable transformation: rotating frame

$$i \frac{d}{dt} \psi = \frac{\hbar \omega}{2} \hat{z}^0 \psi + f(t) \hat{x}^0 \psi$$

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Schödinger equation in the rotating frame

$$i \frac{d}{dt} \psi = \frac{\hbar \omega}{2} \hat{z} \psi + f(t) (\hat{x} \cos(\omega t) + \hat{y} \sin(\omega t)) \psi$$

Variable transformation: rotating frame

$$i \frac{d\mathbf{j}^Q}{dt} = \frac{\omega}{2} \hat{z} + \mathbf{f}(t) (\hat{x} \cos(\omega t) - \hat{y} \sin(\omega t)) \quad (1)$$

$$\mathbf{f}(t) = s(t) \sin(\omega t + \phi) = s(t) \left[\underbrace{\cos(\phi)}_I \sin(\omega t) + \underbrace{\sin(\phi)}_Q \cos(\omega t) \right] \quad (2)$$

$s(t)$ is the envelope function

$I = \cos \phi$ is the in-phase component, $Q = \sin \phi$ is the out-of-phase component

$$i \frac{d\mathbf{j}^Q}{dt} = \frac{\omega}{2} \hat{z} + s(t) [I \sin(\omega t) + Q \cos(\omega t)] (\hat{x} \cos(\omega t) - \hat{y} \sin(\omega t)) \quad (3)$$

Local Oscillator (LO). This generates a **high-frequency carrier** signal at frequency ω_{LO} . It acts as the reference signal for the mixing.

Control signals

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Arbitrary Waveform Generator (AWG). This produces baseband signals (I and Q components) that represent the desired control pulses. These are lower-frequency signals typically shaped for specific qubit operations (e.g., Gaussian or shaped pulses).

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Baseband Pulses (I and Q) These are the output signals from the AWG. The I (In-phase) and Q (Quadrature) components define the amplitude and phase of the control pulses.

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Baseband Pulses (I and Q) These are the output signals from the AWG. The I (In-phase) and Q (Quadrature) components define the amplitude and phase of the control pulses.

IQ Mixer . Combines the carrier signal from the LO with the baseband signals I and Q. This produces a modulated signal, with a frequency $\omega_d = \omega_{LO} - \omega_{AWG}$. This mixing process shifts the baseband signal to the desired frequency range for driving the qubit.

Schrödinger equation in the rotating frame

$$i \frac{d}{dt} \psi = \frac{\hbar}{2} \omega_z \left[\cos(\omega t) \hat{x} + \sin(\omega t) \hat{y} \right] \psi$$

Schrödinger equation in the rotating frame

$$i \frac{d}{dt} |j\rangle_Q = \frac{\hbar \omega}{2} \hat{z} + s(t) [I \sin(\omega t) + Q \cos(\omega t)] (\hat{x} \cos(\omega t) - \hat{y} \sin(\omega t)) \quad 0$$

$$s(t) [I \sin(\omega t) + Q \cos(\omega t)] [\hat{x} \cos(\omega t) + \hat{y} \sin(\omega t)] =$$

Schrödinger equation in the rotating frame

$$i \frac{d}{dt} \begin{pmatrix} j \\ q \end{pmatrix} = \frac{\hbar \omega}{2} \hat{z} \cdot \mathbf{s}(t) [I \sin(\omega t) + Q \cos(\omega t)] (\hat{x} \cos(\omega t) - \hat{y} \sin(\omega t)) \quad 0$$

$$\mathbf{s}(t) [I \sin(\omega t) + Q \cos(\omega t)] [\hat{x} \cos(\omega t) + \hat{y} \sin(\omega t)] =$$

$$\mathbf{s}(t) \left[I \hat{x} \sin(\omega t) \cos(\omega t) + I \hat{y} \sin^2(\omega t) + Q \hat{x} \cos^2(\omega t) + Q \hat{y} \sin(\omega t) \cos(\omega t) \right] =$$

Schödinger equation in the rotating frame

$$i \frac{d}{dt} \begin{pmatrix} j \\ q \end{pmatrix} = \frac{\hbar \omega}{2} \hat{z} \cdot \mathbf{s}(t) [I \sin(\omega t) + Q \cos(\omega t)] (\hat{x} \cos(\omega t) - \hat{y} \sin(\omega t)) \quad 0$$

$$\mathbf{s}(t) [I \sin(\omega t) + Q \cos(\omega t)] [\hat{x} \cos(\omega t) + \hat{y} \sin(\omega t)] =$$

$$\mathbf{s}(t) \left[I \hat{x} \sin(\omega t) \cos(\omega t) + I \hat{y} \sin^2(\omega t) + Q \hat{x} \cos^2(\omega t) + Q \hat{y} \sin(\omega t) \cos(\omega t) \right] =$$

$$\frac{\mathbf{s}(t)}{2} [I \hat{x} \sin(2\omega t) + I \hat{y} [1 - \cos(2\omega t)] + Q \hat{x} [1 + \cos(2\omega t)] + Q \hat{y} \sin(2\omega t)] =$$

Schrodinger equation in the rotating frame

$$i \frac{d}{dt} \psi = \frac{\hbar \omega}{2} \hat{z} \left[s(t) [I \sin(\omega t) + Q \cos(\omega t)] (\hat{x} \cos(\omega t) + \hat{y} \sin(\omega t)) \right] \psi$$

$$s(t) [I \sin(\omega t) + Q \cos(\omega t)] [\hat{x} \cos(\omega t) + \hat{y} \sin(\omega t)] =$$

$$s(t) [I \hat{x} \sin(\omega t) \cos(\omega t) + I \hat{y} \sin^2(\omega t) + Q \hat{x} \cos^2(\omega t) + Q \hat{y} \sin(\omega t) \cos(\omega t)] =$$

$$\frac{s(t)}{2} [I \hat{x} \sin(2\omega t) + I \hat{y} [1 - \cos(2\omega t)] + Q \hat{x} [1 + \cos(2\omega t)] + Q \hat{y} \sin(2\omega t)] =$$

$$\frac{s(t)}{2} [I \hat{y} + Q \hat{x}] + \frac{s(t)}{2} \left[\frac{I \hat{x} + Q \hat{y}}{2} \sin(2\omega t) + \frac{Q \hat{x} - I \hat{y}}{2} \cos(2\omega t) \right]$$

Schrodinger equation in the rotating frame

$$i\hbar \frac{d}{dt} \psi = \left[i\hbar \frac{\omega}{2} \hat{z} + \underbrace{i\hbar \frac{s(t)}{2} [\hat{L}_y + Q\hat{x}]}_{H_{\text{drive}}^{\text{RWA}}} + \underbrace{i\hbar \frac{s(t)}{2} \left(\hat{A} \sin(2\omega_d t) + \hat{B} \cos(2\omega_d t) \right)}_{H_{\text{drive}}^{(2\omega_d)}} \right] \psi$$

$$\underbrace{H_{\text{drive}}^{\text{RWA}}}_{\text{RWA}} = \sim \frac{s(t)}{2} [\hat{L}_y + Q\hat{x}]$$

$$\underbrace{H_{\text{drive}}^{(2\omega_d)}}_{\text{2}\omega_d} = \sim \frac{s(t)}{2} \left(\hat{A} \sin(2\omega_d t) + \hat{B} \cos(2\omega_d t) \right)$$

$$i\hbar \frac{d}{dt} \psi = \left[\frac{\hbar\omega}{2} \hat{z} + H_{\text{drive}}^{\text{RWA}} + H_{\text{drive}}^{(2\omega_d)} \right] \psi$$

Rotating Wave Approximation

$$i\hbar \frac{d}{dt} |\psi\rangle = \left[\frac{\hbar \omega_c}{2} \hat{a}_z + H_{\text{drive}}^{(\text{RWA})} + H_{\text{drive}}^{(2\omega_c)} \right] |\psi\rangle \approx \left[\frac{\hbar \omega_c}{2} \hat{a}_z + H_{\text{drive}}^{(\text{RWA})} \right] |\psi\rangle$$

When $\omega_c \gg \omega_d$, the rapidly oscillating terms in the driving Hamiltonian, denoted as $H_{\text{drive}}^{(2\omega_c)}$, oscillate at frequency $2\omega_c$ and can be neglected.

These terms **average out to zero** over time, as their contribution is negligible on the longer time scales dictated by $\omega_c(t)$ and $\omega_d(t)$.

This simplification is known as the Rotating Wave Approximation (RWA), which retains only the terms responsible for the dominant system dynamics.

Z-control gate

$$\begin{aligned} \dot{U} &= -i \frac{d}{dt} U \\ U(0) &= |0\rangle \end{aligned} \quad \begin{aligned} &= \frac{\theta(t)}{2} \hat{L}_z + s(t) \frac{\theta(t)}{2} (\hat{Q}_x + \hat{L}_y) \end{aligned} \quad 0$$

Z-control gate

$$\begin{aligned} \dot{U} & \approx i \frac{dJ^Q}{dt} = \frac{J(t)}{2} \hat{\Lambda}_z \quad s(t) \frac{1}{2} (Q \hat{\Lambda}_x + I \hat{\Lambda}_y) \\ U(0) & = J_0 i \end{aligned}$$

We **switch-off** the driving, setting $s(t) = 0$

$$\begin{aligned} \dot{U} & \approx i \frac{dJ^Q}{dt} = \frac{J(t)}{2} \hat{\Lambda}_z \quad 0 \quad \text{with} \quad J(t) = J_t(t) - J_d \\ U(0) & = J_0 i \end{aligned}$$

Z-control gate

$$\begin{aligned} \dot{q} &= i \frac{d\varphi}{dt} = \frac{\phi(t)}{2} \hat{z} \quad s(t) \frac{1}{2} (Q \hat{x} + I \hat{y}) \\ \varphi(0) &= j_0 i \end{aligned}$$

We **switch-off** the driving, setting $s(t) = 0$

$$\begin{aligned} \dot{q} &= i \frac{d\varphi}{dt} = \frac{\phi(t)}{2} \hat{z} \quad 0 \quad \text{with} \quad \phi(t) = \phi_t(t) - \phi_d \\ \varphi(0) &= j_0 i \end{aligned}$$

After integration, we arrive at the following solution:

$$\varphi(t) = \exp \left[i \frac{z(t)t}{2} \hat{z} \right] j_0 i \quad \text{with} \quad z(t) = \int_0^t \phi(\tau) d\tau$$

Z-control gate

$$\rho(t) = \exp\left[-i\frac{z(t)t}{2}\hat{\sigma}_z\right] \rho(0) \quad \text{with} \quad z(t) = \int_0^t \dot{z}(t') dt'$$

The initial state is

$$\rho(0) = c_0(t_0)|0\rangle + c_1(t_0)|1\rangle$$

Thus by exploiting the definition of the $\hat{\sigma}_z$ operator [$\hat{\sigma}_z|0\rangle = |0\rangle$; $\hat{\sigma}_z|1\rangle = -|1\rangle$]

$$\rho(t) = c_0(0) \exp\left[-i\frac{z(t)t}{2}\right] |0\rangle + c_1(0) \exp\left[i\frac{z(t)t}{2}\right] |1\rangle$$

which can be also put in the form

$$\rho(t) = \exp\left[-i\frac{z(t)t}{2}\right] \left[c_0(t_0)|0\rangle + c_1(t_0) \exp\left[i\frac{z(t)t}{2}\right] |1\rangle \right]$$

Z-control gate

$$|c^0(t)\rangle = \underbrace{\exp\left[i\frac{z(t)}{2}t\right]}_{c_0^0(t)} |c_0(t_0)\rangle + \underbrace{\exp\left[i\frac{z(t)}{2}t\right] \exp[i z(t)]}_{c_1^0(t)} |c_1(t_0)\rangle$$

$$\underbrace{\exp\left[i\frac{z(t)}{2}t\right]}_{c_0^0(t)} |c_0(t_0)\rangle$$

$$\underbrace{\exp\left[i\frac{z(t)}{2}t\right] \exp[i z(t)]}_{c_1^0(t)} |c_1(t_0)\rangle$$

which can be put in a matrix form

$$c^0(t) = \exp\left[i\frac{z}{2}t\right] Z_z(t) c^0(0)$$

where $Z_z(t) = \begin{pmatrix} 1 & 0 \\ 0 & e^{i z(t)} \end{pmatrix}$ with $z(t) = \int_0^t z(t) dt$

Z-control gate

$$c^0(t) = \exp\left(i \frac{z}{2} t\right) Z_z(t) c^0(0)$$

where $Z_z(t) = \begin{pmatrix} 1 & 0 \\ 0 & e^{i z(t)} \end{pmatrix}$ with $z(t) = \int_0^t \omega_z(t') dt'$

the term $-\frac{\hbar \omega_z}{2} \sigma_z$ in the Hamiltonian enables a rotation around the z -axis of the Bloch sphere through the control of the qubit transition frequency $\omega_z(t)$.

To implement a π -pulse on the z axis, one has to choose the parameters such that $z(\pi) = \pi$:

$$Z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}$$

X-control gate

Let us assume that we now apply a pulse at the qubit frequency ω_q , so that $\Delta = 0$, we have:

$$i \frac{d\mathbf{j}^q}{dt} = s(t) \frac{1}{2} (\hat{Q}_x + \hat{I}_y)$$

$$\mathbf{j}^q(t_0) = j_0 \mathbf{i}$$

an in-phase pulse ($\phi = 0$, I-component) corresponds to rotations around the x-axis

an out-of-phase pulse ($\phi = \pi$, Q-component) corresponds to rotations about the y-axis

$$\hat{Q} = 1$$

$$\hat{I} = 0$$

$$j(t) = J_m s(t) \cos(\phi dt)$$

X-control

$$i \frac{d\mathbf{j}^q}{dt} = s(t) \frac{1}{2} \hat{Q}_x$$

$$\mathbf{j}^q(t_0) = j_0 \mathbf{i} = c_0(0) j_0 \mathbf{i} + c_1(0) j_1 \mathbf{i}$$

X-control

$$i \frac{d|j\rangle_q}{dt} = s(t) \frac{\hat{X}}{2} |j\rangle_q$$

$$|j\rangle_q(t_0) = |j\rangle_q = c_0(0)|j0\rangle + c_1(0)|j1\rangle$$

$$|j\rangle_q(t) = \exp\left[-i \int_{t_0}^t s(\tau) \frac{\hat{X}}{2} d\tau\right] |j\rangle_q$$

$\theta_x(t)$ is the angle by which a state is rotated given the coupling frequency and the waveform envelope $s(t)$.

To implement a π -pulse on the x axis, one has to choose the parameters such that $\theta_x(t) = \pi$ with a driving signal in quadrature with the qubit drive.

X-control gate

$$\rho(t) = \exp\left[-i\frac{\chi}{2}\hat{x}\right] \rho(0) \quad x(t) = Q \int_{t_0}^t s(\tau) d\tau$$

The initial state: $\rho(0) = c_0(t_0)|0\rangle\langle 0| + c_1(t_0)|1\rangle\langle 1|$

$$\rho(t) = \cos\left[\frac{\chi}{2}\right] \hat{1} + i \sin\left[\frac{\chi}{2}\right] \hat{x} [c_0(0)|0\rangle\langle 0| + c_1(0)|1\rangle\langle 1|]$$

X-control gate

$$\rho(t) = \exp\left[-i\frac{\chi}{2}\hat{X}\right] \rho(0) \quad x(t) = Q \int_{t_0}^{t} s(\tau) d\tau$$

The initial state: $\rho(0) = c_0(t_0)|0\rangle + c_1(t_0)|1\rangle$

$$\rho(t) = \cos\left[\frac{\chi}{2}\right] \hat{I} + i \sin\left[\frac{\chi}{2}\right] \hat{X} [c_0(0)|0\rangle + c_1(0)|1\rangle]$$

Thus by exploiting the definition of the \hat{X} operator $\hat{X}|0\rangle = |1\rangle$; $\hat{X}|1\rangle = |0\rangle$

$$\rho(t) = \cos\left[\frac{\chi}{2}\right] [c_0(0)|0\rangle + c_1(0)|1\rangle] + i \sin\left[\frac{\chi}{2}\right] [c_0(0)|1\rangle + c_1(0)|0\rangle]$$

X-control gate

$$\rho(t) = \exp\left[-i\frac{\chi}{2}\hat{X}\right] \rho(0) \quad x(t) = Q \int_{t_0}^{t} s(\tau) d\tau$$

The initial state: $|j_0\rangle = c_0(t_0)|j_0\rangle + c_1(t_0)|j_1\rangle$

$$\rho(t) = \cos\left[\frac{\chi}{2}\right] \hat{I} + i \sin\left[\frac{\chi}{2}\right] \hat{X} [c_0(0)|j_0\rangle + c_1(0)|j_1\rangle]$$

Thus by exploiting the definition of the \hat{X} operator $\hat{X}|j_0\rangle = |j_1\rangle$; $\hat{X}|j_1\rangle = |j_0\rangle$

$$\rho(t) = \cos\left[\frac{\chi}{2}\right] [c_0(0)|j_0\rangle + c_1(0)|j_1\rangle] + i \sin\left[\frac{\chi}{2}\right] [c_0(0)|j_1\rangle + c_1(0)|j_0\rangle]$$

$$\rho(t) = \underbrace{\cos\left[\frac{\chi}{2}\right] c_0(0) + i \sin\left[\frac{\chi}{2}\right] c_1(0)}_{c_0(t)} |j_0\rangle + \underbrace{i \sin\left[\frac{\chi}{2}\right] c_0(0) + \cos\left[\frac{\chi}{2}\right] c_1(0)}_{c_1(t)} |j_1\rangle$$

X-control gate

$$|c_0(t)\rangle = \underbrace{\cos \frac{\chi}{2} c_0(0) + i \sin \frac{\chi}{2} c_1(0)}_{c_0(t)} |z\rangle + \underbrace{i \sin \frac{\chi}{2} c_0(0) + \cos \frac{\chi}{2} c_1(0)}_{c_1} |j0i\rangle$$

X-control gate

$$|c_0(t)\rangle = \underbrace{\cos \frac{x}{2} c_0(0) + i \sin \frac{x}{2} c_1(0)}_{\{z_{c_0(t)}\}} |j0i\rangle + \underbrace{i \sin \frac{x}{2} c_0(0) + \cos \frac{x}{2} c_1(0)}_{\{z_{c_1}\}} |j0i\rangle$$

$$\Re c_0^0(t) = \cos \frac{x}{2} c_0(0) + i \sin \frac{x}{2} c_1(0)$$

$$\Im c_1^0(t) = i \sin \frac{x}{2} c_0(0) + \cos \frac{x}{2} c_1(0)$$

X-control gate

$$c^0(t) = \underbrace{\cos \frac{x}{2} c_0(0) + i \sin \frac{x}{2} c_1(0)}_{c_0(t)} + j0i + \underbrace{i \sin \frac{x}{2} c_0(0) + \cos \frac{x}{2} c_1(0)}_{c_1(t)} j0i$$

$$\Re c_0^0(t) = \cos \frac{x}{2} c_0(0) + i \sin \frac{x}{2} c_1(0)$$

$$\Im c_1^0(t) = i \sin \frac{x}{2} c_0(0) + \cos \frac{x}{2} c_1(0)$$

$$\begin{matrix} c_0^0(t) \\ c_1^0(t) \end{matrix} = i \begin{matrix} 0 & 1 \\ \sin \frac{x}{2} & i \cos \frac{x}{2} \end{matrix} \begin{matrix} c_0(0) \\ c_1(0) \end{matrix}$$

X-control gate

$$c^0(t) = iX_z(t) c^0(0)$$

where $X_z(t) = \begin{pmatrix} \cos \frac{\chi}{2} & \sin \frac{\chi}{2} \\ \sin \frac{\chi}{2} & i \cos \frac{\chi}{2} \end{pmatrix}$ $x(t) = \int_{t_0}^t s(\tau) d\tau$

the term $s(t) \frac{!}{2} \frac{d}{2} \wedge_x$ in the Hamiltonian enables a rotation around the x -axis of the Bloch sphere through the control of the envelope $s(t)$.

X-control gate

$$c^0(t) = iX_z(t) c^0(0)$$

where $X_z(t) = \begin{pmatrix} \cos \frac{\chi}{2} & \sin \frac{\chi}{2} \\ \sin \frac{\chi}{2} & \cos \frac{\chi}{2} \end{pmatrix}$ and $\chi(t) = \int_{t_0}^t s(\tau) d\tau$

the term $s(t) \frac{1}{2} \sigma_x$ in the Hamiltonian enables a rotation around the x-axis of the Bloch sphere through the control of the envelope signal $s(t)$.

To implement a π -pulse on the x axis, one has to choose the parameters such that $\chi(t) = \pi$ with a driving signal in quadrature with the qubit drive.

$$X = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

Y-control gate

Let us assume that we now apply a pulse at the qubit frequency ω_q , so that $\Delta = 0$, we have:

$$i \frac{d\mathbf{j}^q}{dt} = s(t) \frac{1}{2} (\hat{Q}_x + \hat{I}_y)$$

$$\mathbf{j}^q(t_0) = j_0 \mathbf{i}$$

an in-phase pulse ($\phi = 0$, I-component) corresponds to rotations around the x-axis

an out-of-phase pulse ($\phi = \pi$, Q-component) corresponds to rotations about the y-axis

$$\hat{Q} = 0$$

$$\hat{I} = 1$$

$$j(t) = J_m s(t) \sin(\omega_q t)$$

Y-control

$$i \frac{d\mathbf{j}^q}{dt} = s(t) \frac{1}{2} \hat{I}_y$$

$$\mathbf{j}^q(t_0) = j_0 \mathbf{i} = c_0(0) j_0 \mathbf{i} + c_1(0) j_1 \mathbf{i}$$

Y-control gate

$$c^0(t) = iY_y(t) c^0(0)$$

where $Y_y(t) = \begin{matrix} 0 & & 1 \\ \textcircled{A} & i \cos \frac{y}{2} & i \sin \frac{y}{2} \\ & i \sin \frac{y}{2} & i \cos \frac{y}{2} \end{matrix}$ $y(t) = \int_{t_0}^t s(\tau) d\tau$

the term $s(t) \frac{!}{2} \frac{d}{2} \wedge_y$ in the Hamiltonian enables a rotation around the y -axis of the Bloch sphere through the control of the envelope signal $s(t)$.

Y-control gate

$$c^0(t) = iY_y(t) c^0(0)$$

where $Y_y(t) = \int_{t_0}^t s(\tau) d\tau$

$$Y_y(t) = \begin{pmatrix} 0 & i \cos \frac{y}{2} & i \sin \frac{y}{2} \\ i \sin \frac{y}{2} & 0 & i \cos \frac{y}{2} \\ 0 & 0 & 0 \end{pmatrix}$$

the term $s(t) \frac{1}{2} \sigma_y$ in the Hamiltonian enables a rotation around the y -axis of the Bloch sphere through the control of the envelope signal $s(t)$.

To implement a π -pulse on the y -axis, one has to choose the parameters such that $Y_y(t) = \frac{\pi}{2}$ with a driving signal in quadrature with the qubit drive.

$$Y_y = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix}$$

Swap Operation

SWAP

$$j00i \rightarrow j00i$$

$$j10i \rightarrow j01i$$

$$j01i \rightarrow j10i$$

$$j11i \rightarrow j11i$$

$$\text{SWAP} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

iSWAP

$$j00i \rightarrow j00i$$

$$j10i \rightarrow i j01i$$

$$j01i \rightarrow i j10i$$

$$j11i \rightarrow j11i$$

$$\text{iSWAP} = \begin{pmatrix} 0 & 1 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & i & 0 & 0 \\ 0 & 0 & i & 0 & 0 & 0 \\ 0 & i & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 1 & 1 \end{pmatrix}$$

Two coupled transmons

Hamiltonian in the weak-coupling regime

Two degrees of freedom: ϕ_1 and ϕ_2 .

$\phi_1; Q_1; \phi_2; Q_2$ are conjugate variables.

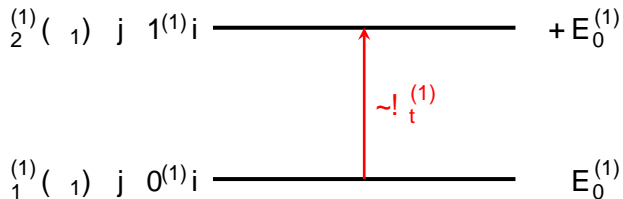
q_1, q_2 are the charges associated with the capacitors C_1, C_2 . Note $q_1 \in Q_1, q_2 \in Q_2$.

Weak coupling regime $C_g \ll C_1, C_2$

In this limit, we have $q_1 \approx Q_1$ and $q_2 \approx Q_2$

$$\mathbb{H} = \frac{q_1^2}{2C_1} + E_{J1} \left[1 - \cos \left(\frac{2\pi}{\Phi_0} \phi_1 \right) \right] + \frac{q_2^2}{2C_2} + E_{J2} \left[1 - \cos \left(\frac{2\pi}{\Phi_0} \phi_2 \right) \right] + \frac{C_g}{C_1 C_2} \phi_1 \phi_2$$

Two-level approximated model: Transmon 1



$$!_t^{(1)} = \frac{q}{8E_{C1}jE_{J1j}} \frac{E_{C1}}{\sim}$$

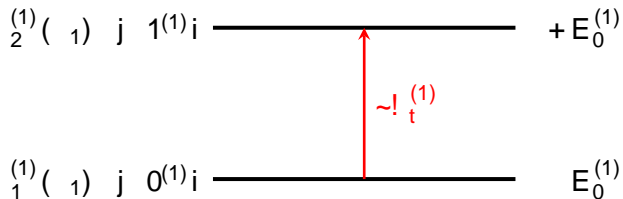
$$H_a^{(1)} = \frac{\sim!_t^{(1)}}{2} \Lambda_z^{(1)}$$

$\Lambda_z^{(1)}$ definition

$$\Lambda_z^{(1)} |0^{(1)}\rangle = |0^{(1)}\rangle$$

$$\Lambda_z^{(1)} |1^{(1)}\rangle = + |1^{(1)}\rangle$$

Two-level approximated model: Transmon 1



$$!_t^{(1)} = \frac{q}{8E_{C1}jE_{J1j}} \frac{E_{C1}}{\sim}$$

$$H_a^{(1)} = \frac{\sim!_t^{(1)}}{2} \Lambda_z^{(1)}$$

$\Lambda_z^{(1)}$ definition

$$\begin{aligned} \langle \Lambda_z^{(1)} | 0^{(1)}_i \rangle &= | 0^{(1)}_i \rangle \\ \langle \Lambda_z^{(1)} | 1^{(1)}_i \rangle &= + | 1^{(1)}_i \rangle \end{aligned}$$

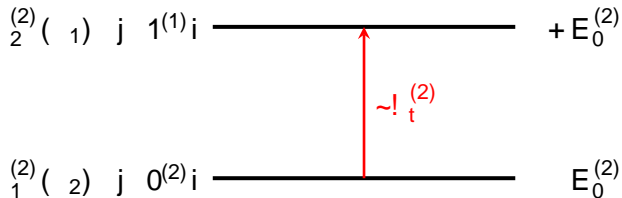
$\delta^{(1)}$ definition

$$\begin{aligned} \langle \delta^{(1)} | 0^{(1)}_i \rangle &= 0 \\ \langle \delta^{(1)} | 1^{(1)}_i \rangle &= | 0^{(1)}_i \rangle \end{aligned}$$

$\delta_+^{(1)}$ definition

$$\begin{aligned} \langle \delta_+^{(1)} | 0^{(1)}_i \rangle &= | 1^{(1)}_i \rangle \\ \langle \delta_+^{(1)} | 1^{(1)}_i \rangle &= 0 \end{aligned}$$

Two-level approximated model: Transmon 2



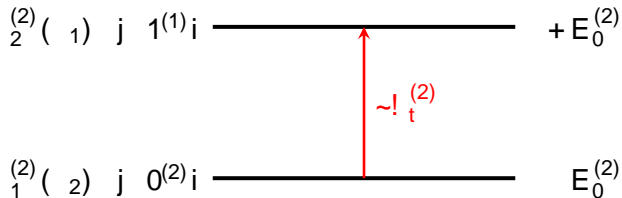
$$\Omega_t^{(2)} = \frac{q}{8E_C 2j E_J 2j} \frac{E_2}{\sim}$$

$$\mathbb{H}_a^{(2)} = \frac{\sim \Omega_t^{(2)}}{2} \Lambda_z^{(2)}$$

$\Lambda_z^{(2)}$ definition

$$\begin{aligned} \Lambda_z^{(2)} |0^{(2)}\rangle &= |0^{(2)}\rangle \\ \Lambda_z^{(2)} |1^{(2)}\rangle &= + |1^{(2)}\rangle \end{aligned}$$

Two-level approximated model: Transmon 2



$$|t^{(2)}| = \sqrt{\frac{q}{8E_C 2jE_J 2j}} \frac{E_2}{\sim}$$

$$\mathbb{H}_a^{(2)} = \frac{\sim |t^{(2)}|}{2} \hat{\Lambda}_z^{(2)}$$

$\hat{\Lambda}_z^{(2)}$ definition

$$\begin{aligned} \hat{\Lambda}_z^{(2)} |0^{(2)}\rangle_j &= |0^{(2)}\rangle_j \\ \hat{\Lambda}_z^{(2)} |1^{(2)}\rangle_j &= + |1^{(2)}\rangle_j \end{aligned}$$

$\hat{J}^{(2)}$ definition

$$\begin{aligned} \hat{J}^{(2)} |0^{(2)}\rangle_j &= 0 \\ \hat{J}^{(2)} |1^{(2)}\rangle_j &= |0^{(2)}\rangle_j \end{aligned}$$

$\hat{J}_+^{(1)}$ definition

$$\begin{aligned} \hat{J}_+^{(1)} |0^{(2)}\rangle_j &= |1^{(2)}\rangle_j \\ \hat{J}_+^{(1)} |1^{(2)}\rangle_j &= 0 \end{aligned}$$

Two-level approximated model: Interaction Terms

$$\mathbb{H}_{\text{int}} = \frac{C_g}{C_1 C_2} \hat{q}_1 \hat{q}_2$$

$$\mathbb{H}_{\text{int}} \sim \int \hat{\Lambda}_x^{(1)} \hat{\Lambda}_x^{(2)}$$

$\hat{\Lambda}_x^{(1)}$ definition

$$\left(\begin{array}{l} \hat{\Lambda}_x^{(1)} j0^{(1)} i = j1^{(1)} i \\ \hat{\Lambda}_x^{(1)} j1^{(1)} i = j0^{(1)} i \end{array} \right.$$

$$\hat{\Lambda}_x^{(1)} j1^{(1)} i = j0^{(1)} i$$

$\hat{\Lambda}_x^{(2)}$ definition

$$\left(\begin{array}{l} \hat{\Lambda}_x^{(2)} j0^{(2)} i = j1^{(2)} i \\ \hat{\Lambda}_x^{(2)} j1^{(2)} i = j0^{(2)} i \end{array} \right.$$

$$\hat{\Lambda}_x^{(2)} j1^{(2)} i = j0^{(2)} i$$

Two-level approximated model: Interaction Terms

$$\mathbb{H}_{\text{int}} = \frac{C_g}{C_1 C_2} q_1 q_2$$

$$\mathbb{H}_{\text{int}} = \sim_{\text{int}} \hat{\Lambda}_x^{(1)} \hat{\Lambda}_x^{(2)}$$

$\hat{\Lambda}_x^{(1)}$ definition

$$\begin{cases} \hat{\Lambda}_x^{(1)} j_{0^{(1)}} i = j_{1^{(1)}} i \\ \hat{\Lambda}_x^{(1)} j_{1^{(1)}} i = j_{0^{(1)}} i \end{cases}$$

$\hat{\Lambda}_x^{(2)}$ definition

$$\begin{cases} \hat{\Lambda}_x^{(2)} j_{0^{(2)}} i = j_{1^{(2)}} i \\ \hat{\Lambda}_x^{(2)} j_{1^{(2)}} i = j_{0^{(2)}} i \end{cases}$$

$$\mathbb{H}_{\text{int}} = \frac{1}{\sim} \frac{C_g}{C_1 C_2} q^{(1)} q^{(2)}$$

$$q^{(1)} = \sum_{0=2}^Z + \sum_{0=2}^Z \frac{1}{i} \frac{d_0^{(1)}}{d} d$$

$$q^{(2)} = \sum_{0=2}^Z + \sum_{0=2}^Z \frac{1}{i} \frac{d_0^{(2)}}{d} d$$

Circuit Hamiltonian in a two-level approximation

$$\mathbb{H} = \frac{Q_1^2}{2C_1} + E_{J1} \cos \frac{\varphi_1}{2} + \frac{Q_2^2}{2C_2} + E_{J2} \cos \frac{\varphi_2}{2} + \frac{C_g}{C_1 C_2} \varphi_1 \varphi_2$$

$$\mathbb{H} = \frac{\hbar}{2} \sum_i \sigma_x^{(i)} + \frac{\hbar}{2} \sum_i \sigma_x^{(i)} \sigma_x^{(i+1)}$$

$$\dot{\psi}_j = -i \mathbb{H} \psi_j$$

Tensor product between vector spaces

Let V and U be two linear vector spaces, of dimensions N_V and N_U respectively

Let $\{ |v_1\rangle, |v_2\rangle, \dots \}$ be the basis of V

Let $\{ |u_1\rangle, |u_2\rangle, \dots \}$ be the basis of U , respectively.

Vectors and operators of these spaces are denoted with an index, (v) , depending on whether they belong to V or U .

Tensor product between vector spaces

Let V and U be two linear vector spaces, of dimensions N_V and N_U respectively

Let $\{ |v_1\rangle ; |v_2\rangle ; \dots \}$ be the basis of V

Let $\{ |u_1\rangle ; |u_2\rangle ; \dots \}$ be the basis of U , respectively.

Vectors and operators of these spaces are denoted with an index, (v) , depending on whether they belong to V or U .

By definition, the vector space W is called the **tensor product** of V and U

$$W = V \otimes U$$

Tensor product between vector spaces

the set of vectors $\{v_m\}_{m=1}^g$ and $\{u_n\}_{n=1}^g$ constitutes a basis for V ;

the tensor product is **distributive**

$$[j'(v)_i] [j(u)_i] = [j'(v)_i + j_2(v)_i] [j(u)_i]$$

$$[j'(v)_i] [j(u)_i] = [j'(v)_i] [j(u)_i + j_2(u)_i]$$

the tensor product is **linear**

$$j'(v)_i [j_1(u)_i + j_2(u)_i] = j_1'(v)_i j_1(u)_i + j_2'(v)_i j_2(u)_i$$

$$[j_1'(v)_i + j_2'(v)_i] [j(u)_i] = j_1'(v)_i j(u)_i + j_2'(v)_i j(u)_i$$

The scalar products in V and U permits us to define a **scalar product** in $V \otimes U$ as well. Let be

$$j'(v); (u)_i \quad j'(v)_i j(u)_i \quad \text{and} \quad \langle v; u \rangle = \langle v \rangle \langle u \rangle :$$

$$\langle v; u \rangle j'(v); (u) = \langle v \rangle j'(v) \langle u \rangle j(u)$$

Tensor product of operators

We consider a linear operator A defined in V .

We introduce \tilde{A} acting in W , which we call the **extension of A in W** , defined in the following way:

$$\tilde{A}([j] \otimes |v\rangle_i) = [A(j)] \otimes |v\rangle_i$$

Tensor product of operators

We consider a linear operator $A(v)$ defined in V .

We introduce $\tilde{A}(v)$ acting in W , which we call the **extension of $A(v)$ in W** , defined in the following way:

$$\tilde{A}(v)[j' (v)i \ j (u)i] = [A(v)j' (v)i] \ j (u)i$$

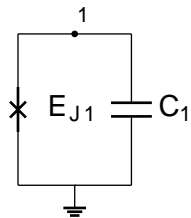
Now let $A(v)$ and $B(u)$ be two linear operators acting respectively in V and U .

Their **tensor product $\tilde{A}(v) \otimes B(u)$** is the linear operator in W , such as

$$[\tilde{A}(v) \otimes B(u)][j' (v)i \ j (u)i] = [A(v)j' (v)i] \ [B(u)j (u)i]$$

State space of two qubits

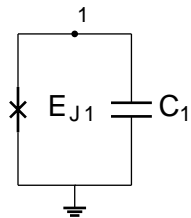
For $C_g \neq 0$ the two qubits decouple



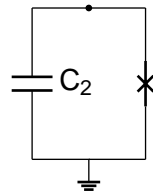
$$|1\rangle^{(1)} = c_0^{(1)} |0\rangle^{(1)} + c_1^{(1)} |1\rangle^{(1)}$$

State space of two qubits

For $C_g \neq 0$ the two qubits decouple



$$|^{(1)}E\rangle = c_0^{(1)} |0^{(1)}\rangle + c_1^{(1)} |1^{(1)}\rangle$$



$$|^{(2)}E\rangle = c_0^{(2)} |0^{(2)}\rangle + c_1^{(2)} |1^{(2)}\rangle$$

State space of two qbits

A **basis** for the state space $\mathcal{S} = \mathcal{S}^{(1)} \otimes \mathcal{S}^{(2)}$ is given by the set of orthonormal kets

$$|j00\rangle = |0^{(1)}\rangle \otimes |0^{(2)}\rangle;$$

$$|j01\rangle = |0^{(1)}\rangle \otimes |1^{(2)}\rangle$$

$$|j10\rangle = |1^{(1)}\rangle \otimes |0^{(2)}\rangle$$

$$|j11\rangle = |1^{(1)}\rangle \otimes |1^{(2)}\rangle$$

State space of two qbits

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$$|j00\rangle = |0\rangle^{(1)} \otimes |0\rangle^{(2)} ;$$

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$$|j10\rangle = |1\rangle^{(1)} \otimes |0\rangle^{(2)}$$

$$|j11\rangle = |1\rangle^{(1)} \otimes |1\rangle^{(2)}$$

$$|\psi(t)\rangle = c_{00}(t)|j00\rangle + c_{01}(t)|j01\rangle + c_{10}(t)|j10\rangle + c_{11}(t)|j11\rangle$$

$$1 = |c_{00}|^2 + |c_{01}|^2 + |c_{10}|^2 + |c_{11}|^2$$

Schrödinger equation in the rotating frame

At $t = 0$ the state of the quantum circuit is $|j\rangle = |j\rangle(0)$

$$|j\rangle(0) = c_{00}(0)|j00\rangle + c_{01}(0)|j01\rangle + c_{10}(0)|j10\rangle + c_{11}(0)|j11\rangle$$

To find the state of the circuit $|j\rangle(t)$ at time t , we have to solve the Schrödinger equation

$$i\hbar \frac{d}{dt} |j\rangle(t) = \mathbb{H} |j\rangle(t)$$

$$|j\rangle(0) = |j\rangle(0)$$

$$\mathbb{H} = + \frac{\hbar \omega_z}{2} \Lambda_z^{(1)} \Lambda_z^{(2)} + \hbar \omega_x \Lambda_x^{(1)} \Lambda_x^{(2)} + \hbar \omega_y \Lambda_y^{(1)} \Lambda_y^{(2)}$$

Variable transformation: rotating frame

We solve the problem in a new variable φ .

Variable transformation: rotating frame

We solve the problem in a new variable ρ .

At time t , the Bloch sphere representation of each qubit is rotated clockwise about the z -axis by an angle $\theta(t) = + \omega t$ with respect to the Bloch sphere representation of

$$\mathcal{R}_z^{(h)}(\rho(t)) = e^{i \frac{\omega}{2} Z^{(h)}} = \exp\left(-i \theta(t) \frac{\hat{Z}^{(h)}}{2}\right) \quad \theta(t) = \omega t \quad \hbar = 2 \hbar f; 2g$$

Variable transformation: rotating frame

We solve the problem in a new variable ρ .

At time t , the Bloch sphere representation of each qubit is rotated clockwise about the z -axis by an angle $\theta(t) = + \int_t^t \omega dt$ with respect to the Bloch sphere representation of

$$\mathcal{R}_z^{(h)}(\rho(t)) = e^{i \int_t^t \omega dt} \rho(t) = \exp\left(-i \int_t^t \frac{\omega}{2} dt\right) \rho(t) = \exp\left(-i \int_t^t \frac{\hbar \omega}{2} dt\right) \rho(t)$$

$$\mathcal{R}(t) = \mathcal{R}_z^{(1)}(\rho(t)) \mathcal{R}_z^{(2)}(\rho(t)) = \exp\left(-i \int_{t_0}^t \omega dt\right) \rho(t) \exp\left(-i \int_{t_0}^t \omega dt\right) \rho(t)$$

Coupled Qubits in the Rotating Wave Approximation

To find the state of the circuit $|\psi(t)\rangle$ at time t , we have to solve the Schrödinger equation

$$i\hbar \frac{d}{dt} |\psi(t)\rangle = H_{int} |\psi(t)\rangle$$

$$|\psi(0)\rangle = |\psi_0\rangle$$

$$\hat{H} = \hbar \omega_{int} \left(\frac{\sigma_x^{(1)}}{2} + \frac{\sigma_x^{(2)}}{2} \right) + \hbar \omega_{c1} \left(\frac{\sigma_y^{(1)}}{2} + \frac{\sigma_y^{(2)}}{2} \right) e^{-i2\omega_{c1} t} + \hbar \omega_{c2} \left(\frac{\sigma_y^{(1)}}{2} + \frac{\sigma_y^{(2)}}{2} \right) e^{+i2\omega_{c2} t}$$

Coupled Qubits in the Rotating Wave Approximation

To find the state of the circuit $|\psi(t)\rangle$ at time t , we have to solve the Schrödinger equation

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$$\hat{H} = \hbar \omega_{int} \left(\frac{1}{2} \sigma_x^{(1)} \sigma_x^{(2)} + \frac{1}{2} \sigma_y^{(1)} \sigma_y^{(2)} + \frac{1}{2} \sigma_z^{(1)} \sigma_z^{(2)} \right) e^{-i2\omega t} + \left(\frac{1}{2} \sigma_x^{(1)} \sigma_x^{(2)} + \frac{1}{2} \sigma_y^{(1)} \sigma_y^{(2)} - \frac{1}{2} \sigma_z^{(1)} \sigma_z^{(2)} \right) e^{+i2\omega t}$$

Disregarding the oscillating terms at frequency 2ω we obtain (rotating wave approximation):

$$\hat{H} = \hbar \omega_{int} \left(\frac{1}{2} \sigma_x^{(1)} \sigma_x^{(2)} + \frac{1}{2} \sigma_y^{(1)} \sigma_y^{(2)} - \frac{1}{2} \sigma_z^{(1)} \sigma_z^{(2)} \right) + \left(\frac{1}{2} \sigma_x^{(1)} \sigma_x^{(2)} + \frac{1}{2} \sigma_y^{(1)} \sigma_y^{(2)} + \frac{1}{2} \sigma_z^{(1)} \sigma_z^{(2)} \right) e^{+i2\omega t}$$

Rotating Wave Approximation

$$i\hbar \frac{d}{dt} \begin{pmatrix} \psi_1(t) \\ \psi_2(t) \end{pmatrix} = \hat{H}_{\text{int}} \begin{pmatrix} \psi_1^{(1)} \\ \psi_2^{(2)} \end{pmatrix} + \begin{pmatrix} \psi_1^{(1)} \\ \psi_2^{(2)} \end{pmatrix} + \begin{pmatrix} \psi_1^{(2)} \\ \psi_2^{(1)} \end{pmatrix}$$

We **expand the unknown state** $\begin{pmatrix} \psi_1(t) \\ \psi_2(t) \end{pmatrix}$ in terms of the four basis states of S:

$$\begin{pmatrix} \psi_1(t) \\ \psi_2(t) \end{pmatrix} = c_{00}(t) \begin{pmatrix} 0 \\ 0 \end{pmatrix} + c_{01}(t) \begin{pmatrix} 0 \\ 1 \end{pmatrix} + c_{10}(t) \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_{11}(t) \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

Our goal is to determine the 4 coefficients, which are function of time and subjected to the normalization condition.

Rotating Wave Approximation

$$i\hbar \frac{d}{dt} \begin{pmatrix} \psi_1(t) \\ \psi_2(t) \end{pmatrix} = \hat{H} \begin{pmatrix} \psi_1(t) \\ \psi_2(t) \end{pmatrix}$$

We **expand the unknown state** $|\psi(t)\rangle$ in terms of the four basis states of S:

$$|\psi(t)\rangle = c_{00}(t)|00\rangle + c_{01}(t)|01\rangle + c_{10}(t)|10\rangle + c_{11}(t)|11\rangle$$

Our goal is to determine the 4 coefficients, which are function of time and subjected to the normalization condition.

We substitute this expansion in the Schrödinger equation

Rotating Wave Approximation

$$i\hbar \frac{d}{dt} \begin{pmatrix} (1) \\ (2) \end{pmatrix} = \begin{pmatrix} - & + \\ + & - \end{pmatrix} \begin{pmatrix} (1) \\ (2) \end{pmatrix} + \begin{pmatrix} (1) \\ (2) \end{pmatrix} \begin{pmatrix} (1) \\ (2) \end{pmatrix}$$

$$\begin{pmatrix} (1) \\ (2) \end{pmatrix}(t_0) = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

We **expand the unknown state** $\begin{pmatrix} (1) \\ (2) \end{pmatrix}(t)$ in terms of the four basis states of S:

$$\begin{pmatrix} (1) \\ (2) \end{pmatrix}(t) = c_{00}(t)|00\rangle + c_{01}(t)|01\rangle + c_{10}(t)|10\rangle + c_{11}(t)|11\rangle$$

Our goal is to determine the 4 coefficients, which are function of time and subjected to the normalization condition.

We substitute this expansion in the Schrödinger equation

The operators $\begin{pmatrix} (1) \\ + \end{pmatrix} \begin{pmatrix} (2) \\ - \end{pmatrix}$ and $\begin{pmatrix} (1) \\ - \end{pmatrix} \begin{pmatrix} (2) \\ + \end{pmatrix}$ will q-bitwise act on the four basis states accordingly to the definition of $\begin{pmatrix} (1) \\ \pm \end{pmatrix}$ and $\begin{pmatrix} (2) \\ \pm \end{pmatrix}$

We project the resulting equation along each of the four basis states of S , obtaining:

$$\begin{array}{lll}
 \dot{c}_{00}(t) = 0 & \dot{c}_{00}(t) = \text{const} & \dot{c}_{00}(t) = \text{const} \\
 \dot{c}_{01}(t) = -i \int c_{10}(t) & \ddot{c}_{01}(t) = -\frac{2}{\int} c_{01}(t) & c_{01}(t) = +K_+ e^{+i \int t} + K_- e^{-i \int t} \\
 \dot{c}_{10}(t) = -i \int c_{01}(t) & c_{10}(t) = i / \int \dot{c}_{01}(t) & c_{10}(t) = -K_+ e^{+i \int t} + K_- e^{-i \int t} \\
 \dot{c}_{11}(t) = 0 & \dot{c}_{11}(t) = \text{const} & \dot{c}_{11}(t) = \text{const}
 \end{array}$$

We enforce initial conditions at initial time.

$$\begin{array}{lll}
 c_{00}(t=0) = c_{00}(0), & \dot{c}_{00}(t) = c_{00}(0) & \\
 c_{01}(t=0) = c_{01}(0), & c_{01}(0) = +K_+ + K_- & 2K_- = c_{01}(0) + c_{10}(0) \\
 c_{10}(t=0) = c_{10}(0), & c_{10}(0) = -K_+ + K_- & 2K_+ = c_{01}(0) - c_{10}(0) \\
 c_{11}(t=0) = c_{11}(0), & \dot{c}_{11}(t) = c_{00}(0) &
 \end{array}$$

The two coupled qubits, initially in the state:

$$|0\rangle = c_{00}(0)|00\rangle + c_{01}(0)|01\rangle + c_{10}(0)|10\rangle + c_{11}(0)|11\rangle$$

after a time t their state (in the rotating frame) is:

$$|t\rangle = c_{00}(t)|00\rangle + c_{01}(t)|01\rangle + c_{10}(t)|10\rangle + c_{11}(t)|11\rangle$$

where the coefficients are the following time-functions

$$c_{00}(t) = c_{00}(0)$$

$$c_{01}(t) = c_{01}(0) \cos(\int \text{int} t) - i c_{10}(0) \sin(\int \text{int} t)$$

$$c_{10}(t) = -i c_{01}(0) \sin(\int \text{int} t) + c_{10}(0) \cos(\int \text{int} t)$$

$$c_{11}(t) = c_{11}(0)$$

Matrix representation of the evolution operator

The coefficient can be also represented in a matrix form as:

$$\mathbf{c}(t) = \begin{pmatrix} c_{00}(t) \\ c_{01}(t) \\ c_{10}(t) \\ c_{11}(t) \end{pmatrix} \quad \mathbf{c}(t) = \mathbf{U}(t)\mathbf{c}(0) \quad \mathbf{U}(t) = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & \cos(\int \omega dt) & -i \sin(\int \omega dt) & 0 \\ 0 & i \sin(\int \omega dt) & \cos(\int \omega dt) & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Matrix representation of the evolution operator

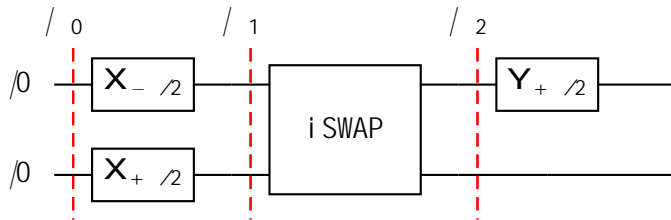
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The two qubits are tuned in resonance, $\omega_1 = \omega_2$ for a time interval t such that $\int_0^t \Omega dt = \frac{\pi}{2}$,

$$i\text{SWAP} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -i & 0 \\ 0 & -i & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

Bell State Generation



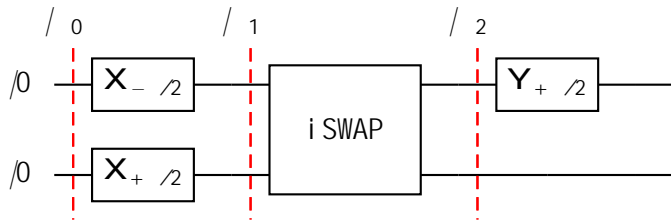
$$\mathbf{X} = \begin{pmatrix} -i \cos \frac{x}{2} & \sin \frac{x}{2} \\ \sin \frac{x}{2} & -i \cos \frac{x}{2} \end{pmatrix};$$

$$\mathbf{X}_{\pm}/2 = \frac{1}{2} \begin{pmatrix} -i & \pm 1 \\ \pm 1 & -i \end{pmatrix};$$

$$\mathbf{Y} = -i \begin{pmatrix} \cos \frac{y}{2} & \sin \frac{y}{2} \\ -\sin \frac{y}{2} & \cos \frac{y}{2} \end{pmatrix}$$

$$\mathbf{Y}/2 = -\frac{i}{2} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}$$

Bell State Generation

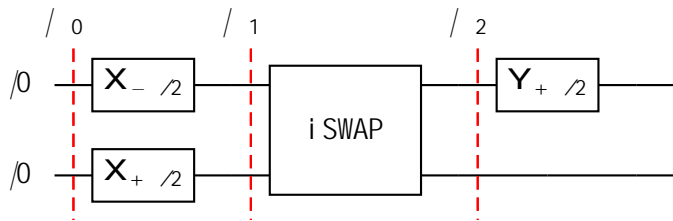


$$X_{\pm} \pi/2 = \frac{1}{2} \begin{pmatrix} 1 & -i & \pm 1 & 0 \\ \pm 1 & -i & -i & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}; \quad i \text{ SWAP} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -i & 0 \\ 0 & -i & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}; \quad Y = \begin{pmatrix} -\frac{i}{2} & 1 & 1 \\ -1 & -1 & 1 \end{pmatrix}$$

$$X_{-\pi/2} \quad X_{+\pi/2} = \frac{1}{2} \begin{pmatrix} -1 & -i & +i & -1 \\ -i & -1 & -1 & +i \\ +i & -1 & -1 & -i \\ -1 & +i & -i & -1 \end{pmatrix}; \quad Y_{\pi/2} \quad I = -\frac{i}{2} \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{pmatrix}$$

Bell State Generation

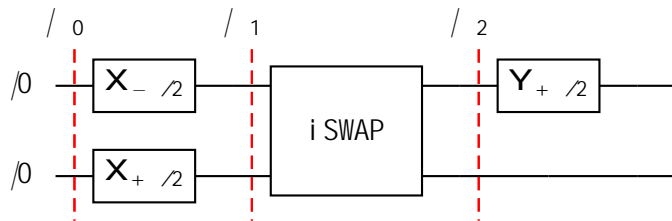
$$|0\rangle = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}$$



$$X_- / 2 \quad X_+ / 2 = \frac{1}{2} \begin{pmatrix} -1 & -i & +i & -1 \\ -i & -1 & -1 & +i \\ +i & -1 & -1 & -i \\ -1 & +i & -i & -1 \end{pmatrix} \quad |1\rangle = X_- / 2 \quad X_+ / 2 |0\rangle = \frac{1}{2} \begin{pmatrix} -1 \\ -i \\ +i \\ -1 \end{pmatrix}$$

Bell State Generation

$$| \psi_1 \rangle = \frac{1}{2} \begin{pmatrix} -1 \\ i \\ -i \\ -1 \end{pmatrix}$$

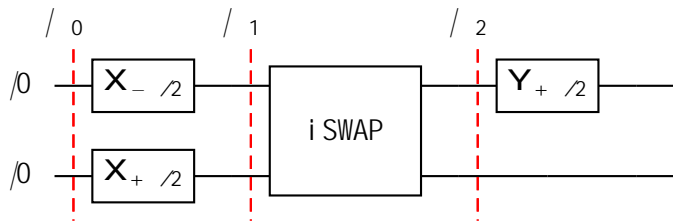


$$i \text{ SWAP} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & -i & 0 \\ 0 & -i & 0 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

$$|\psi_2\rangle = i \text{ SWAP} |\psi_1\rangle = \frac{1}{2} \begin{pmatrix} 1 \\ -1 \\ 1 \\ 1 \end{pmatrix}$$

Bell State Generation

$$| \psi \rangle_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ -1 \\ 1 \\ 1 \end{pmatrix}$$



$$Y_{\sqrt{2}} \mathbf{I} = -\frac{i}{2} \begin{pmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 \\ -1 & 0 & 1 & 0 \\ 0 & -1 & 0 & 1 \end{pmatrix}$$

$$| \psi \rangle_3 = Y_{\sqrt{2}} \mathbf{I} | \psi \rangle_2 = \frac{i}{2} \begin{pmatrix} 1 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$